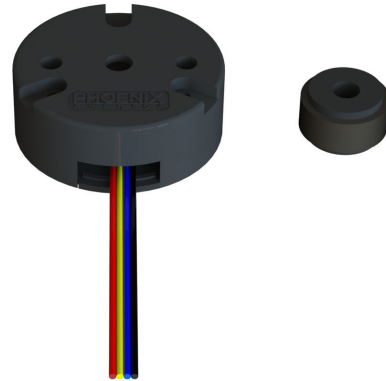


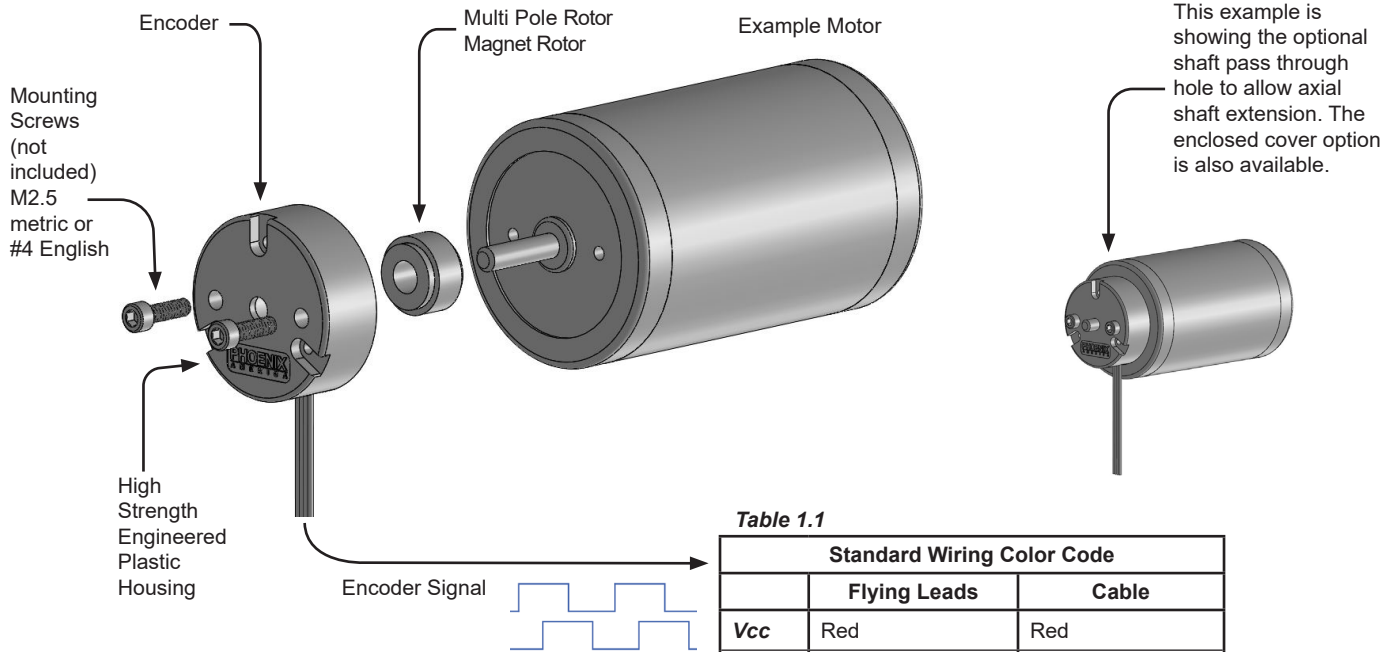
**Features and Benefits**

- 30 mm O.D. Miniature size
- Magnetic technology offers robust performance.
- 100% Non-contacting design (no bearings or bushings) provides an extremely long life and is tolerant to harsh environments.
- Simple two piece design (magnet rotor + encoder) for easy alignment and installation.
- Bi-directional two channel incremental quadrature output.
- Mounting holes for 2-bolt (.750" B.H.C. x .125" O.D.) or 3-bolt pattern (.823" B.C x .078" O.D.)
- Target magnet for standard shaft sizes from 2 mm to 8mm. Custom bore size available.
- Options for up to 10 pulses per channel per revolution.
- Customizable lead wires, cables, and or connectors.



Kit - Encoder with Magnet Rotor  
Shown with shaft pass through hole  
Wire color order varies with part configuration

**Application Example**

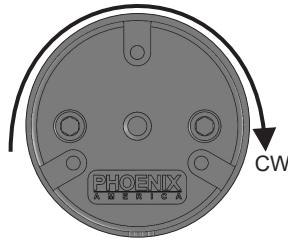
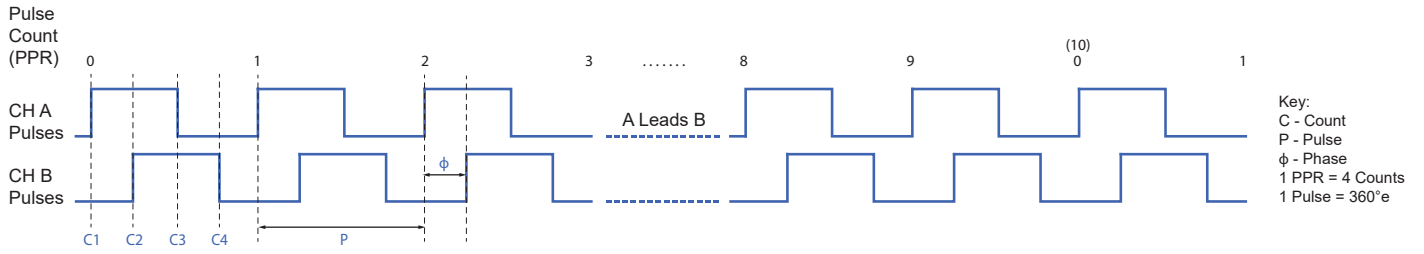


**Table 1.1**

Standard Wiring Color Code		
	Flying Leads	Cable
<b>Vcc</b>	Red	Red
<b>Gnd</b>	Black	Black
<b>Ch A</b>	Yellow	Brown
<b>Ch B</b>	Blue	Orange

Other colors available upon request.  
Contact [sales@phoenixamerica.com](mailto:sales@phoenixamerica.com).

**Output Waveforms**



Channel A leads Channel B for clockwise shaft rotation (shaft rotation is defined when looking at the branded face of the encoder).

**Absolute Maximum Ratings**

Table 2.1

Characteristic	Symbol	Rating	Units
Forward Supply Voltage	$V_{CC}$	32	V
Reverse Supply Voltage	$V_{RCC}$	-0.3	V
Output Voltage	$V_{OUT}$	32	V
Continuous Output Current	$I_{OUT}$	20	mA
Operating Temperature	$T_A$	-40 - 125	°C
Storage Temperature	$T_S$	-40 - 150	°C

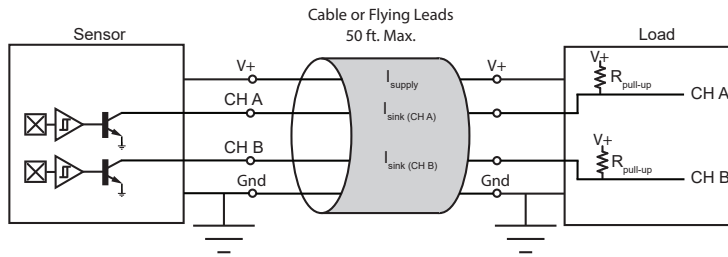
**Electrical Characteristics**

Table 2.2

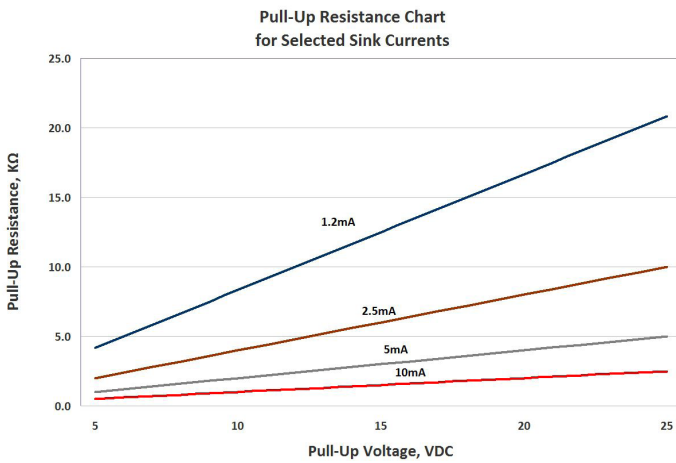
Characteristic	Symbol	Test Conditions	Min.	Typ. <sup>1</sup>	Max.	Unit <sup>2</sup>
Forward Supply Voltage	$V_{CC}$	Operating, $T_J < 165\text{ °C}$	4.0	-	24	V
Supply Current	$I_{CC}$	$V_{CC} = 4\text{ to }24\text{V}$	1.4	3.0	5.6	mA
Output Current	$I_{SINK}$	$V_{CC} = 4\text{ to }24\text{V}$	-	-	15	mA
Output Frequency	$f_{OUT}$	$V_{CC} = 4\text{ to }24\text{V}$	-	-	30	kHz

Higher output frequencies available upon request. Contact [sales@phoenixamerica.com](mailto:sales@phoenixamerica.com).

**Electrical Circuit**



Output channels require customer supplied pull-up resistors unless internal pull-up option is selected. See Table 3.1 for recommended resistor values.



**Table 3.1**

Recommended Pull-Up Resistor Values			
	Supply Voltage		
Current, $I_{sink}$	5	12	24
1.2 mA	4.3K	10.0K	20.0K
2.5 mA	2.0K	4.7K	10.0K
5 mA	1.0K	2.4K	4.7K
10 mA	510Ω	1.2K	2.4K

$I_{sink}$  is application dependent. It is recommended to use the lowest possible sink current when selecting a pull-up resistor.

Theoretical Pull-Up Resistor Calculation:  $R_{pullup} = \frac{V_{supply}}{I_{sink}}$

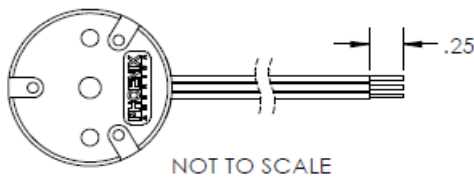
Resistance values based on closest standard 5% resistor values

Absolute Maximum  $I_{sink} = 20mA$

4.7 K pull-up is available as a standard option. If an alternative pull-up value is preferred, contact sales@phoenixamerica.com.

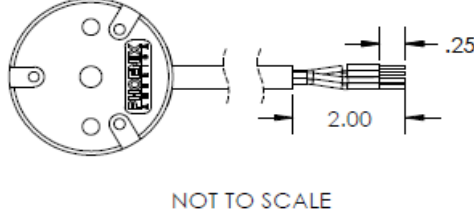
**Wiring**

**FLYING LEADS**



- 24 AWG
- 7x32 Strands, Tinned Copper
- PVC Insulation
- MIL M16878/1
- Temperature Rating: 105°C

**CABLE**



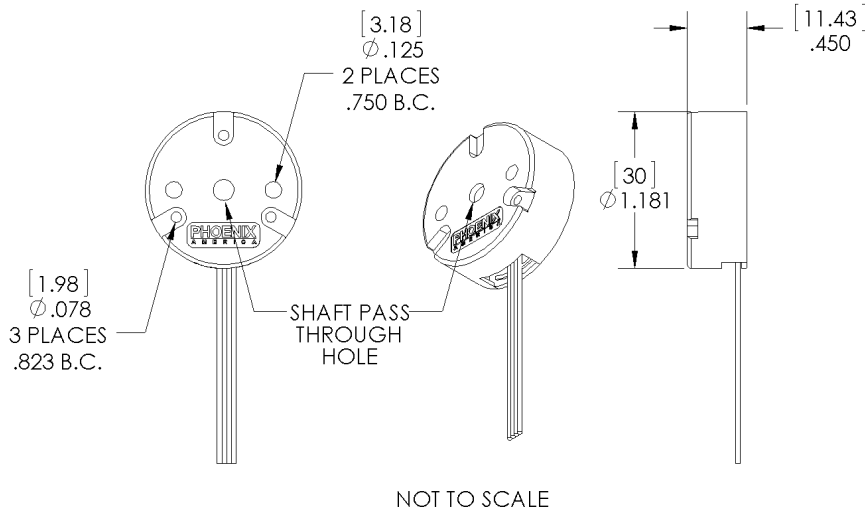
- 24 AWG
- 4 Conductor with Foil Shield and Drain
- Stranded Tinned Copper
- PVC Insulation
- Grey PVC Jacket
- UL Style 2464, CSA
- Temperature Rating: 105°C

**Table 3.2**

Standard Wiring			
	Leads	Cable	Connector Pin-Out
<b>Ch A</b>	Yellow	Brown	1
<b>Ch B</b>	Blue	Orange	2
<b>Gnd</b>	Black	Black	3
<b>Vcc</b>	Red	Red	4

Custom lengths and insulation materials available. Contact sales@phoenixamerica.com.

**Encoder Physical Outline**



**Table 4.1**

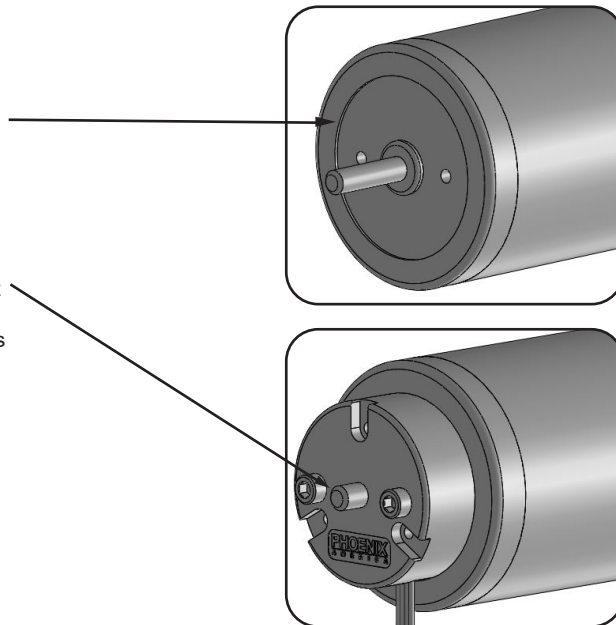
Motor Shaft Diameter	Shaft Pass Through Hole Size (options/recommendation)	
-	No Hole	
2 mm	2.06 mm	0.081 in
3 mm	3.06 mm	0.120 in
1/8 in	3.26 mm	0.127 in
5/32 in	4.06 mm	0.160 in
4 mm	4.06 mm	0.160 in
3/16 in	4.83 mm	0.190 in
5 mm	5.06 mm	0.199 in
6 mm	6.06 mm	0.239 in
1/4 in	6.40 mm	0.252 in
7 mm	7.06 mm	0.278 in
5/16 in	8.05 mm	0.317 in
8 mm	8.05 mm	0.317 in

Other shaft pass through hole sizes available upon request. Contact [sales@phoenixamerica.com](mailto:sales@phoenixamerica.com).

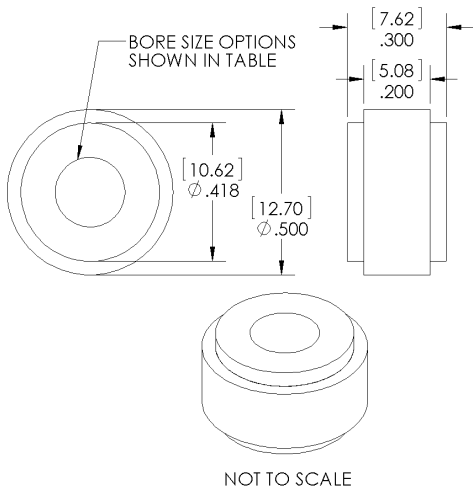
**Encoder Mounting Guidelines**

Concentricity of the encoder housing to the magnet rotor is critical for optimal encoder performance. Considering the following during the design phase will ensure concentricity and ease of assembly.

- Tight molding tolerances allow for the outside diameter of the encoder to be used to locate the encoder housing concentric to the motor shaft and magnet rotor. A machined pocket on the motor endbell works well for alignment. Recommended pocket is 0.015" to 0.020" deep and 1.191" in diameter.
- Extending the shaft through the optional shaft pass through hole is an easy way to align the encoder housing to the motor shaft and magnet rotor. Simply position the encoder so that the shaft is centered concentrically in the shaft pass through hole.
- If previous two methods of alignment are not used it is recommended that the encoder be fastened to the motor using #5-40 or M3 mounting screws. The slightly larger diameter of the #5-40 and M3 screws will compensate for some of the tolerance allowed when using the standard recommended #4-40 or M2.5 mounting screws.



**Magnet Rotor Physical Outline - Engineered Polymer Hub (Mounting Style H)**



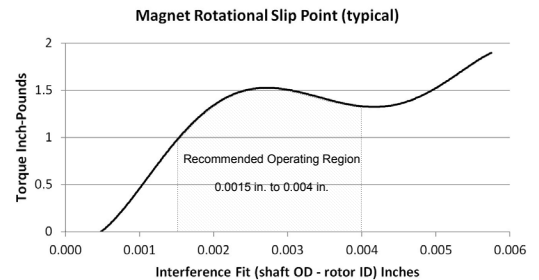
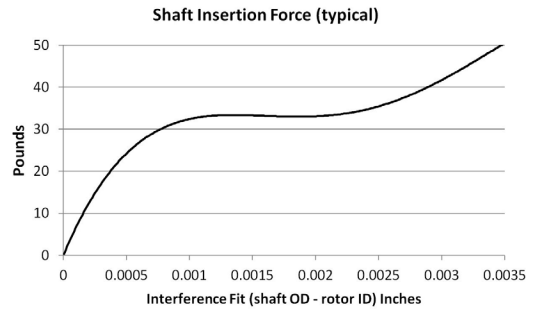
**Table 5.1**

Bore Size (.inch)	Motor Shaft OD Size (nominal)	NEMA Guide Shaft Tolerance	Magnet Bore MIN. (inch)	Magnet Bore MAX. (inch)
079	2 mm (.0787")	+0.0000"/-0.0005"	.0727	.0757
118	3 mm (.1181")		.1121	.1151
125	1/8 in (.1250")		.1190	.1220
156	5/32 in (.1563")		.1503	.1533
157	4 mm (.1575")		.1515	.1545
188	3/16 in (.1875")		.1815	.1845
197	5 mm (.1969")		.1909	.1939
236	6 mm (.2364")		.2304	.2334
250	1/4 in (.2500")		.2440	.2470
276	7 mm (.2758")		.2698	.2728
313	5/16 in (.3125")		.3065	.3095
315	8 mm (.3150")		.3090	.3120

Other bore sizes available upon request.  
Contact [sales@phoenixamerica.com](mailto:sales@phoenixamerica.com).

**Magnet Rotor Mounting Guidelines - Engineered Polymer Hub (Mounting Style H) For Press Fit Application**

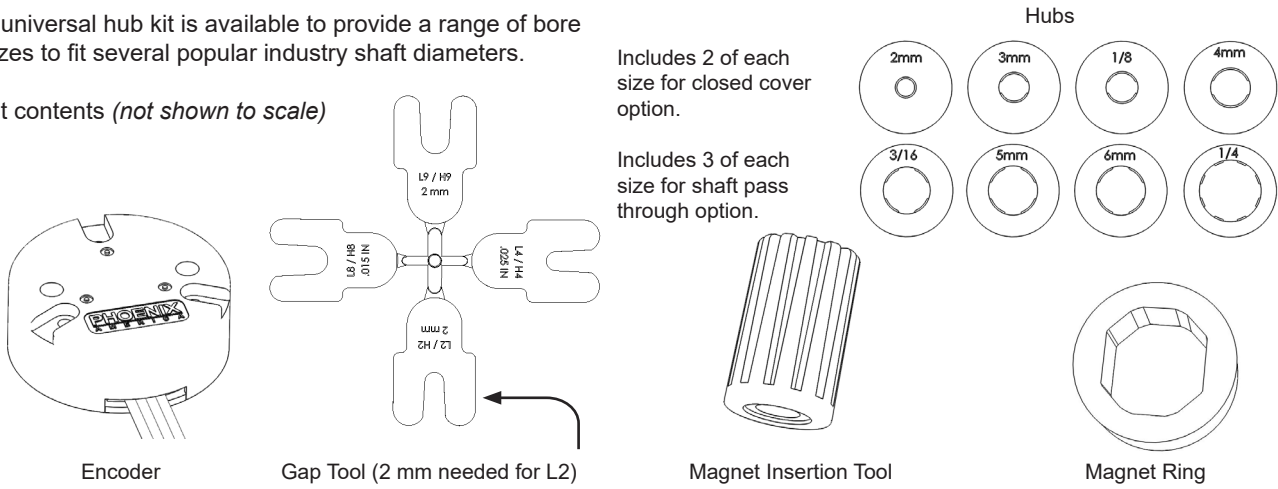
- Proper alignment of the magnet rotor to the encoder sensing element is critical for optimal encoder performance. Insure that the magnet rotor is mounted to the specified height shown below.
- A machined step on the motor shaft provides a quick and repeatable method for positioning the magnet rotor. Spacers or other fixturing should be used if no mechanical locating features are on the shaft.
- A chamfered lead in on the shaft will aid in aligning the magnet rotor.
- Prior to insertion, the motor shaft should be clean and free of any oils, lubricants, or solvents.
- Proper fixtures and support must be used to ensure the magnet is pressed on straight and aligned with the motor shaft.
- Opposite end of motor shaft should be supported to avoid undue stress on motor bearings during the pressing operation.
- In applications with high torque or environmental extremes, a retaining compound can be used to enhance the strength of the press fit.



**Magnet Rotor Physical Outline - Universal Hub (Mounting Style U)**

A universal hub kit is available to provide a range of bore sizes to fit several popular industry shaft diameters.

Kit contents (*not shown to scale*)



Includes 2 of each size for closed cover option.

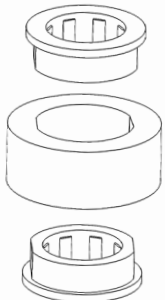
Includes 3 of each size for shaft pass through option.

**Assembly Guidelines**

**Without shaft pass-through option**

Step 1

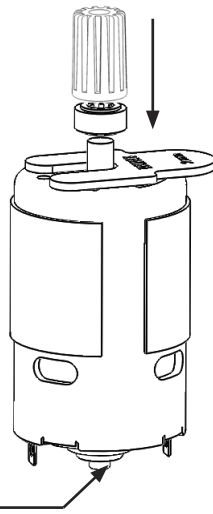
Attach two of the desired hub size on each side of the magnet. Make sure the flats are in-line with each other.



Step 2

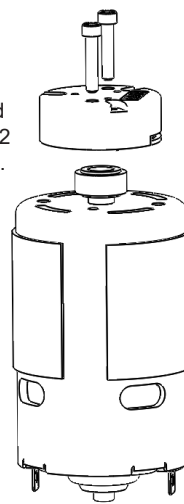
Use the insertion tool to push the magnet assembly **straight** onto the shaft until the bottom face of the hub is resting on the 2 mm gap tool.

*tip* - Support the bottom of the motor with a fixture or holding clamp.



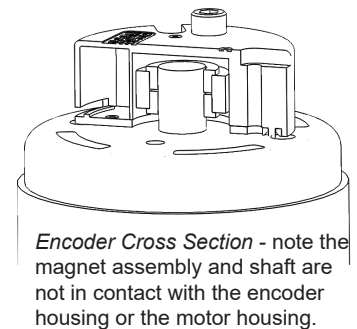
Step 3

Place the encoder onto the motor and secure with #2 or M2 screws.



Step 4

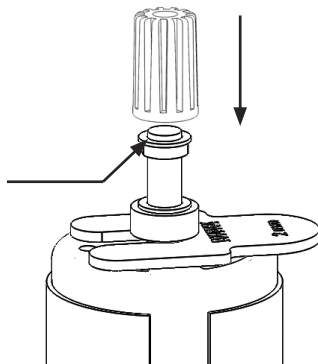
Manually spin the shaft to verify that the shaft/magnet is not interfering with the encoder.



**With shaft pass-through option**

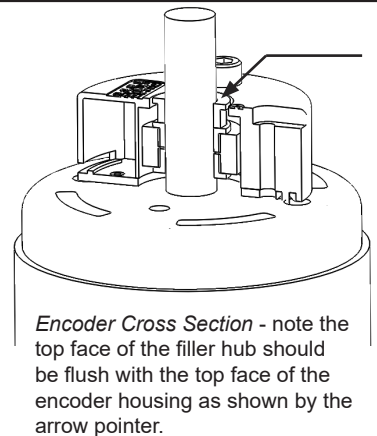
Step 2a

Insert an additional hub piece as shown. This is used as a space filler to match the opening in the encoder housing.



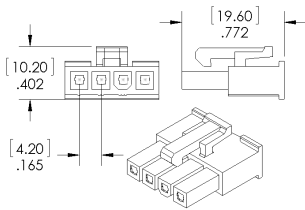
Step 3a

Place the encoder onto the motor and secure with #2 or M2 screws.

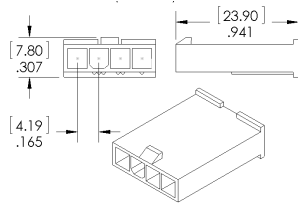


**Connector Options**

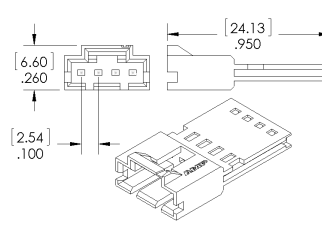
Molex Mini-Fit Jr. (Male)



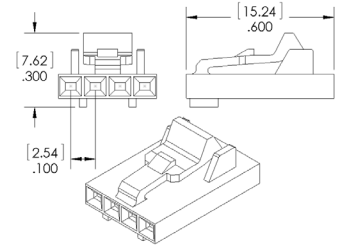
Molex Mini-Fit Jr. (Female)



TE AmpModu MTE (Male)



TE AmpModu MTE (Female)



Need a different connector? Contact [sales@phoenixamerica.com](mailto:sales@phoenixamerica.com).

**Part Number Description**

Series	PPR	Bore Size	Supply Voltage	Index	Output Type	Shaft Pass Through Hole	Magnet Rotor Mounting	Wiring	Length (Meters)	Connector
L2	0004 0005 0006 0008 0010	0079 2 mm 0118 3 mm 0125 1/8 in 0156 5/32 in 0157 4 mm 0188 3/16 in (default) 0197 5 mm 0236 6 mm 0250 1/4 in 0276 7 mm 0313 5/16 in 0315 8 mm 0000 Universal Hub	05 5V	N No (default) Y Yes	C Open Collector (default) S Open Collector with Internal 4.7k Pull Up Resistor	N None (default) Y Size will match bore shown in Table 4.1	H Engineered Polymer Hub U Universal Hub	F Flying Leads (default) C Cable	A .5 (19.685") B 0.914 (36") (default) C 1 (39.370") D 2 (78.740")	XX None (default) A1 TE AmpModu MTE (Male) A2 TE AmpModu MTE (Female) M1 Molex Mini-Fit Jr. (Male) M2 Molex Mini-Fit Jr. (Female)

Example: L2-0010-0188-05-N-C-N-H-F-B-XX