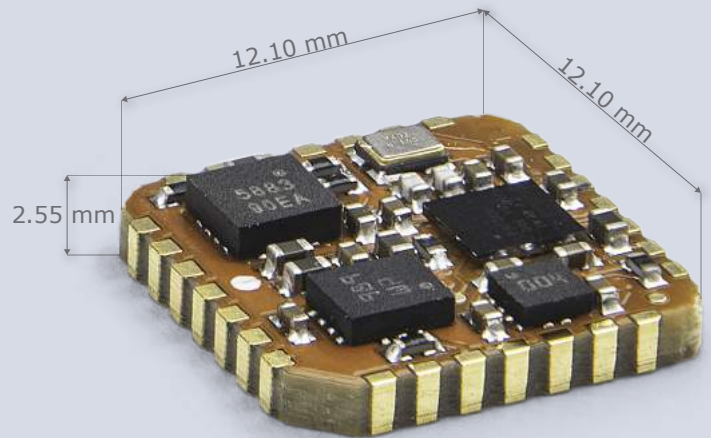# MTi-3

- **Smallest form factor on the market**
- **Easy integration**
- **Development Kit available**

The MTi-3 is the smallest self-contained Attitude Heading and Reference System (AHRS) on the market. The Xsens optimized strapdown algorithm (AttitudeEngine ™) performs high-speed, dead-reckoning calculations at 1 kHz, accurately capturing high-frequency motions. Xsens' industry-leading sensor fusion algorithm provides high accuracy and sensor auto-calibration in this cost-effective module for a wide range of (embedded) applications. It relieves you of the work of designing, integrating and maintaining gyroscopes, accelerometers and other sensors.

The MTi-3 is part of the MTi 1-series supported by the MT Software Suite, which includes MT Manager (GUI for Windows/Linux), SDK, example codes and drivers for many platforms.

12.10 mm · 12.10 mm · 2.55 mm

- 3D models available on request
- Available online via Digi-Key, Mouser, Farnell and local distributors
- For full specifications: please refer to the MTi-series datasheet available at mtidocs.xsens.com

Sensor fusion performance

Roll, Pitch	0.5 deg RMS
Yaw/Heading	2 deg RMS
Strapdown Integration (SDI)	Yes

Gyroscope

Standard full range	2000 deg/s
In-run bias stability	10 deg/h
Bandwidth (-3dB)	230 Hz
Noise Density	0.003 º/s/√Hz
g-sensitivity (calibr.)	0.001 º/s/g

Accelerometer

Standard full range	16 g
In-run bias stability	30 µg
Bandwidth (-3dB)	230 Hz
Noise Density	70 µg/√Hz

Magnetometer

Standard full range	+/- 8 G
Total RMS noise	0.5 mG
Non-linearity	0.2%
Resolution	0.25 mG

GNSS Receiver

GNSS receiver interface	n/a
GNSS precision	n/a
RTCM input port	n/a

Barometer

Barometer interface	n/a

Mechanical

IP-rating	IP00
Operating Temperature	-40 to 85 ºC
Casing material	PCB
Mounting orientation	No restriction, full 360º in all axes
Dimensions	12.1 x 12.1 x 2.55 mm
Connector	SMD, footprint compatible with JEDEC PLCC-28
Weight	0.6 g

Electrical

Input voltage	2.19 to 3.6V
Power consumption (typ)	44 mW @ 3V

Interfaces / IO

Interfaces	UART, SPI, I²C
Sync Options	Yes
Protocols	Xbus
Clock drift	10 ppm
Output Frequency	Up to 1 kHz, 100 Hz SDI
Built-in-self test	Gyr, Acc, Mag

Software Suite

GUI (Windows/Linux)	MT Manager Firmware updater, Magnetic Field Mapper
SDK (Example code)	C++, C#, python, Matlab, Nucleo, public source code
Drivers	LabVIEW, ROS, GO
Support	BASE by XSENS: online manuals, community and knowledge base